

1. Use the Laplace transform to solve the initial value problem  $y'' + 4y' + 8y = \sin 5t$ ,  $y(0) = 1$ ,  $y'(0) = -2$ . Many of you were a bit careless with grouping around the transform of the first derivative last time we did a Laplace problem - be careful about that! As we had been doing, convert the equation into the  $s$  variable using the tables, solve for  $Y(s)$  and use Wolfram to do the inverse transform.

2. Write each of the following initial value problems for systems of equations in the form  $\mathbf{x}' = A\mathbf{x} + \mathbf{f}$ ,  $\mathbf{x}(0) = \mathbf{c}$ .

$$(a) \quad \begin{array}{ll} x_1' - 2x_2 = 3 & x_1(0) = 0 \\ x_2' - x_1 + x_2 = -t^2 & x_2(0) = -1 \end{array} \quad (b) \quad \begin{array}{ll} x_1' + 3x_1 - 5x_2 = e^{-t} & x_1(0) = 2 \\ x_2' - 4x_1 + 3x_2 = 3e^{-t} & x_2(0) = 1 \end{array}$$

$$(c) \quad \begin{array}{ll} x_1' + x_1 - 3x_2 + 2x_3 = 0 & x_1(0) = 3 \\ x_2' + 2x_1 + x_2 - 4x_3 = 3 & x_2(0) = -1 \\ x_3' - x_1 + 5x_2 + 2x_3 = \sin 3t & x_3(0) = 2 \end{array} \quad (d) \quad \begin{array}{ll} x_1' + 5x_2 - 2x_3 = \sin t & x_1(0) = 0 \\ x_2' - x_1 + 2x_3 = 0 & x_2(0) = 1 \\ x_3' - 2x_1 - 3x_2 = \cos t & x_3(0) = 0 \end{array}$$

There is another exercise on the back.

3. Convert the ODE  $x^{(4)} + 5x^{(3)} - 7x'' + 3x' - 4x = 0$  (here  $x^{(4)}$  means the fourth derivative of  $x$ ) into a system of first order equations as follows.

(a) Solve the ODE for  $x^{(4)}$ .

(b) Let  $x_1 = x$ ,  $x_2 = x'$ , on up until you have renamed  $x^{(3)}$ . **Write these down, including the ones I've already given you.**

(c) Substitute these into your result for (a), then rearrange the right side so that the indices of  $x$  are increasing. **You are not replacing  $x^{(4)}$  yet!**

(d) Now  $x^{(4)}$  is the first derivative of one of your  $x_k$ . Figure out which one, take its derivative and substitute for  $x^{(4)}$ .

(e) You now have equations for each of  $x'_1$  through  $x'_4$ , scattered about. Write them all as a list now.

(f) As done in Exercise 2, write your result from (e) in the form  $\mathbf{x}' = A\mathbf{x}$ . The matrix  $A$  will have lots of zeros and several ones in it.