Trigonometric Functions of Special Angles

| $\alpha$, degrees | $\alpha$, radians | $\sin \alpha$ | $\cos \alpha$ | $\tan \alpha$ |
| :---: | :---: | :---: | :---: | :---: |
| $0^{\circ}$ | 0 | 0 | 1 | 0 |
| $30^{\circ}$ | $\frac{\pi}{6}$ | $\frac{1}{2}$ | $\frac{\sqrt{3}}{2}$ | $\frac{1}{\sqrt{3}}$ |
| $45^{\circ}$ | $\frac{\pi}{4}$ | $\frac{\sqrt{2}}{2}$ | $\frac{\sqrt{2}}{2}$ | 1 |
| $60^{\circ}$ | $\frac{\pi}{3}$ | $\frac{\sqrt{3}}{2}$ | $\frac{1}{2}$ | $\sqrt{3}$ |
| $90^{\circ}$ | $\frac{\pi}{2}$ | 1 | 0 | undefined |

Trigonometric Functions of an Acute Angle of a Right Triangle

$$
\sin \alpha=\frac{\text { opp }}{\text { hyp }}, \quad \cos \alpha=\frac{\text { adj }}{\text { hyp }}, \quad \tan \alpha=\frac{\text { opp }}{\text { adj }}
$$



## Pythagorean Identity

$$
\sin ^{2} \alpha+\cos ^{2} \alpha=1
$$

Sum and Difference Identities

$$
\begin{array}{ll}
\cos (\alpha+\beta)=\cos \alpha \cos \beta-\sin \alpha \sin \beta & \cos (\alpha-\beta)=\cos \alpha \cos \beta+\sin \alpha \sin \beta \\
\sin (\alpha+\beta)=\sin \alpha \cos \beta+\cos \alpha \sin \beta & \sin (\alpha-\beta)=\sin \alpha \cos \beta-\cos \alpha \sin \beta
\end{array}
$$

## Double Angle Identities

$$
\sin 2 x=2 \sin x \cos x
$$

$$
\cos 2 x=\cos ^{2} x-\sin ^{2} x=2 \cos ^{2} x-1=1-2 \sin ^{2} x
$$

## Complex Numbers

A complex number $z$ is a number of the form $z=x+i y$, where $x$ and $y$ are real numbers and $i^{2}=-1$. The numbers $x$ and $y$ are called the real part and imaginary part of $z$, denoted by $\operatorname{Re} z$ and $\operatorname{Im} z$.

## Complex Conjugates

The complex conjugate (or just conjugate) of a number $z=x+i y$ is the number $\bar{z}=x-i y$. The following hold:

$$
\overline{z_{1} \pm z_{2}}=\bar{z}_{1} \pm \bar{z}_{2} \quad \overline{z_{1} z_{2}}=\bar{z}_{1} \bar{z}_{2} \quad \overline{\left(\frac{z_{1}}{z_{2}}\right)}=\frac{\bar{z}_{1}}{\bar{z}_{2}} \quad \operatorname{Re} z=\frac{z+\bar{z}}{2} \quad \operatorname{Im} z=\frac{z-\bar{z}}{2 i}
$$

## Modulus of a Complex Number

The modulus (or absolute value) of a number $z=x+i y$ is the real number $|z|=\sqrt{x^{2}+y^{2}}$. The following hold:

$$
\begin{gathered}
|z|^{2}=z \bar{z} \quad\left|z_{1} z_{2}\right|=\left|z_{1}\right|\left|z_{2}\right| \quad|\bar{z}|=|z| \quad\left|z_{1}+z_{2}\right| \leq\left|z_{1}\right|+\left|z_{2}\right| \\
\left| \pm z_{1} \pm z_{2}\right| \leq\left|z_{1}\right|+\left|z_{2}\right| \quad\left| \pm z_{1} \pm z_{2}\right| \geq\left|\left|z_{1}\right|-\left|z_{2}\right|\right| \quad\left|\sum_{k=1}^{n} z_{k}\right| \leq \sum_{k=1}^{n}\left|z_{k}\right|
\end{gathered}
$$

## Argument of a Complex Number

For any complex number $z=x+i y$, there exist real numbers $r \geq 0$ and $p h i$ such that

$$
z=x+i y=r(\cos \phi+i \sin \phi) .
$$

This is sometimes called the polar form of $z$. The radian value $\phi$ is an argument of $z$, denoted by $\phi=\arg z$. Note the following:

- If $\phi$ is an argument of $z$, then so is $\phi+2 \pi n$ for any integer $n$.
- The value of $\phi$ (there is only one) such that $-\pi<\phi \leq \pi$ is called the principal $\operatorname{argument}$ of $z$, denoted by $\operatorname{Arg} z$.
- $r=|z|$


## Euler's Formula and Exponential Form

- For any real number $\phi$ we define $e^{i \phi}=\cos \phi+i \sin \phi$. This is called Euler's formula.
- Using Euler's formula, for any complex number $z$ there exists a real number $\phi$ such that

$$
z=r(\cos \phi+i \sin \phi)=r e^{i \phi} .
$$

$r e^{i \phi}$ is called the exponential form of $z$.

## Topology of the Complex Plane

In all of the following and throughout our course, it is understood that a set $S$ under discussion is a subset of the complex plane.

- For $z_{0} \in \mathbb{C}$ and $\varepsilon>0$ the set $D_{\varepsilon}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<\varepsilon\right.$ is called an $\varepsilon$ neighborhood of $z_{0}$.
- A point $z_{0}$ is an interior point of $S$ if there is an $\varepsilon$ neighborhood of $z_{0}$ that contains only points of $S$.
- A point $z_{0}$ is an exterior point of $S$ if there is an $\varepsilon$ neighborhood of $z_{0}$ that contains no points of $S$.
- A point $z_{0}$ is a boundary point of $S$ if every $\varepsilon$ neighborhood of $z_{0}$ contains points of $S$ and points not in $S$.
- A set $S$ is open if every point of $S$ is an interior point.
- A set $S$ is closed if $S$ contains all of its boundary points.
- The set of all boundary points of $S$ is called the boundary of $S$, denoted by $\partial S$.
- The closure of a set $S$ is the union of $S$ with all its boundary. The closure of $S$ is denoted $\bar{S}$ or $\partial S$.
- An open set $S$ is connected if any two points of $S$ can be joined by a polygonal line segment.
- A point $z_{0}$ is called an accumulation point of a set $S$ if every $\varepsilon$ neighborhood of $z_{0}$ contains some point in $S$ other than $z_{0}$.
- A point $z_{0} \in S$ is called an isolated point if there exists an $\varepsilon$ neighborhood of $z_{0}$ containing no points of $S$ other than $z_{0}$.


## Deleted Neighborhood

A deleted neighborhood of a point $z_{0}$ is a set of the form

$$
\left\{z \in \mathbb{C}: 0<\left|z-z_{0}\right|<\varepsilon\right\}
$$

for some $\varepsilon>0$. Given this, an accumulation point $z_{0}$ of a set $S$ is a point such that every deleted neighborhood of $z_{0}$ contains at least one point in $S$.

## Function

A function $f$ is a rule that assigns to each $z \in G$, where $G$ is some subset of $\mathbb{C}$, a unique complex number $w$. We indicate this by writing $w=f(z)$.

- We sometimes say that $z$ is mapped to $w$ by $f$, and that $f$ is a mapping from the complex numbers to the complex numbers.
- The number $w$ is called the image of $z$.
- The set $G$ is called the domain of $f$, and the range of $f$ is the set

$$
\{w \in \mathbb{C}: w=f(z) \text { for some } z \in G\}
$$

## Definition 2.1: Limit of a Function (Churchill and Brown)

Suppose a function $f$ is defined at all points in a deleted neighborhood of a point $z_{0}$. We say that the limit of $f$ as $z$ approaches $z_{0}$ is a number $w_{0}$ if, for every $\varepsilon>0$, there exists a $\delta>0$ such that

$$
\left|f(z)-w_{0}\right|<\varepsilon \quad \text { whenever } \quad 0<\left|z-z_{0}\right|<\delta
$$

We write $\lim _{z \rightarrow z_{0}} f(z)=w_{0}$.

## Definition 2.1: Limit of a Function (Beck, Marchesi, Pixton, Sabalka)

Suppose $f$ is a complex function with domain $G$ and $z_{0}$ is an accumulation point of $G$. Suppose there is a complex number $w_{0}$ such that for every $\varepsilon>0$, we can find a $\delta>0$ so that for all $z \in G$ satisfying $0<\left|z-z_{0}\right|<\delta$ we have $\left|f(z)-w_{0}\right|<\varepsilon$. Then $w_{0}$ is the limit of $f$ as $z$ approaches $z_{0}$, and we write $\lim _{z \rightarrow z_{0}} f(z)=w_{0}$.

## Lemma 2.4: Limit Rules

Let $f$ and $g$ be complex functions and let $c$ and $z_{0}$ be complex numbers. If $\lim _{z \rightarrow z_{0}} f(z)$ and $\lim _{z \rightarrow z_{0}} g(z)$ exist, then
( $\left.\mathrm{a}_{1}\right) \lim _{z \rightarrow z_{0}}[f(z)+g(z)]=\lim _{z \rightarrow z_{0}} f(z)+\lim _{z \rightarrow z_{0}} g(z)$
( $\mathrm{a}_{2}$ ) $\lim _{z \rightarrow z_{0}}[c g(z)]=c \lim _{z \rightarrow z_{0}} g(z)$
(b) $\lim _{z \rightarrow z_{0}}[f(z) \cdot g(z)]=\left[\lim _{z \rightarrow z_{0}} f(z)\right] \cdot\left[\lim _{z \rightarrow z_{0}} g(z)\right]$
(c) If $\lim _{z \rightarrow z_{0}} g(z) \neq 0$, then $\lim _{z \rightarrow z_{0}}\left[\frac{f(z)}{g(z)}\right]=\frac{\lim _{z \rightarrow z_{0}} f(z)}{\lim _{z \rightarrow z_{0}} g(z)}$

## Definition 2.7: Derivative of a Function

Suppose $f: G \rightarrow \mathbb{C}$ is a complex function and $z_{0}$ is an interior point of $G$. The derivative of $f$ at $z_{0}$ is defined as

$$
f^{\prime}\left(z_{0}\right)=\lim _{z \rightarrow z_{0}} \frac{f(z)-f\left(z_{0}\right)}{z-z_{0}}
$$

when the limit exists. In this case we say that $f$ is differentiable at $z_{0}$.

## Holomorphic and Entire Functions

We say that $f$ is holomorphic at $z_{0}$ if it is differentiable at all points in some open disk centered at $z_{0}$, and $f$ is holomorphic on an open set $G$ if it is differentiable at all points in $G$. A function that is differentiable at all points in $\mathbb{C}$ is called entire.

## Lemma 2.11: Derivative Rules

Suppose that $f$ and $g$ are differentiable at $z \in \mathbb{C}, c \in \mathbb{C}$ and $n \in \mathbb{Z}$ and $h$ is differentiable at $g(z)$. Then
(a) $[c f(z)]^{\prime}=c f^{\prime}(z)$ and $[f(z)+g(z)]^{\prime}=f^{\prime}(z)+g^{\prime}(z) \quad$ (linearity)
(b) $[f(z) \cdot g(z)]^{\prime}=f(z) g^{\prime}(z)+g(z) f^{\prime}(z) \quad$ (product rule)
(c) $\left[\frac{f(z)}{g(z)}\right]^{\prime}=\frac{g(z) f^{\prime}(z)-f(z) g^{\prime}(z)}{[g(z)]^{2}} \quad$ (quotient rule)
(d) $(c)^{\prime}=0,(z)^{\prime}=1$ and $\left(z^{n}\right)^{\prime}=n z^{n-1} \quad$ (power rule)
(e) $\left[h(g(z)]^{\prime}=h^{\prime}(g(z)) \cdot g^{\prime}(z) \quad\right.$ (chain rule)

## Theorem 2.15: Cauchy-Riemann Equations

(a) Suppose that $f(z)=f(x+i y)=u(x, y)+i v(x, y)$ is differentiable at $z_{0}=x_{0}+i y_{0}$. Then

$$
\begin{equation*}
u_{x}\left(x_{0}, y_{0}\right)=v_{y}\left(x_{0}, y_{0}\right) \quad \text { and } \quad u_{y}\left(x_{0}, y_{0}\right)=-v_{x}\left(u_{0}, y_{0}\right) \tag{1}
\end{equation*}
$$

(b) Suppose that $f(z)=f(x+i y)=u(x, y)+i v(x, y)$ is a complex valued function such that the first partial derivatives of $u$ and $v$ with respect to both $x$ and $y$ exist in an open disk centered at $z_{0}$ and are continuous at $z_{0}$. If (1) holds at $z_{0}$, then $f$ is differentiable at $z_{0}$.

In both cases the derivative is given by $f^{\prime}\left(z_{0}\right)=u_{x}\left(x_{0}, y_{0}\right)+i v_{x}\left(x_{0}, y_{0}\right)$

## Definition 3.15: The Complex Exponential Function

The complex exponential function $e^{z}$ or $\exp (z)$ is defined for $z=x+i y$ by

$$
\exp (z)=e^{x}(\cos y+i \sin y)=e^{x} e^{i y}
$$

## Lemma 3.16: Properties of the Complex Exponential Function

For all $z, z_{1}, z_{2} \in \mathbb{C}$,
(a) $\exp \left(z_{1}\right) \exp \left(z_{2}\right)=\exp \left(z_{1}+z_{2}\right)$
(b) $\exp (-z)=\frac{1}{\exp (z)}$
(c) $\exp (z+2 \pi i)=\exp (z)$
(d) $|\exp (z)|=\exp (\operatorname{Re} z)$
(e) $\exp (z) \neq 0$
(f) $\frac{d}{d z} \exp (z)=\exp (z)$

## Definition 3.17: The Complex Sine and Cosine Functions

The complex sine and cosine functions are defined for all $z \in \mathbb{C}$ by

$$
\sin z=\frac{\exp (i z)-\exp (-i z)}{2 i} \quad \text { and } \quad \cos z=\frac{\exp (i z)+\exp (-i z)}{2}
$$

## Definition 3.20(A): The Multiple-Valued Complex Logarithm Function

For the complex number $z \neq 0$ with any particular argument $\theta$ we define

$$
\log z=\ln |z|+i(\theta+2 n \pi), \quad n \in \mathbb{Z}
$$

It is then the case that $e^{\log z}=z$ and $\log e^{z}=z+2 n \pi i, \quad n \in \mathbb{Z}$.

## Definition 3.20(b): The Principal Value Complex Logarithm Function

For any complex number $z \in D^{*}=\left\{z: z \neq r e^{i \pi}, r \geq 0\right\}$ we define

$$
\log z=\ln |z|+i \operatorname{Arg} z
$$

Then $e^{\log z}=z, \log e^{z}=z$ and $\frac{d}{d z} \log z=\frac{1}{z}$ for all $z \in D^{*}$.

## Definition 1.14: Paths, Arcs, Contours

A path (or curve, or arc) in $\mathbb{C}$ is the image of a continuous function $\gamma:[a, b] \rightarrow \mathbb{C}$, where $[a, b]$ is a closed interval in $\mathbb{R}$. The function $\gamma$ is the parametrization of the path. We also have the following:

- The path (arc) is called smooth if it is differentiable.
- The path is called a closed curve If $\gamma(a)=\gamma(b)$. It is a simple closed curve if $\gamma(s)=\gamma(t)$ only for $s=a$ and $t=b$.
- A path is called piecewise smooth if there exist $c_{1}<c_{2}<\ldots \ldots<c_{n}$ in the interval $(a, b)$ such that $\gamma$ is smooth on each of the intervals $\left[a, c_{1}\right],\left[c_{1}, c_{2}\right], \ldots,\left[c_{n}, b\right]$. A piecewise smooth curve is sometimes called a contour.


## Definition 4.1: Complex Integration

Suppose $\gamma$ is a smooth curve (arc) parameterized by $\gamma(t), a \leq t \leq b$, and $f$ is a complex function that is continuous on $\gamma$. Then we define the integral of $f$ on $\gamma$ by

$$
\int_{\gamma} f=\int_{\gamma} f(z) d z=\int_{a}^{b} f(\gamma(t)) \gamma^{\prime}(t) d t
$$

If $\gamma(t), a \leq t \leq b$ is a piecewise smooth curve (contour) that is differentiable on the intervals $\left[a, c_{1}\right],\left[c_{1}, c_{2}\right],\left[c_{2}, c_{3}\right], \ldots,\left[c_{n-1}, c_{n}\right],\left[c_{n}, b\right]$, then

$$
\int_{\gamma} f=\int_{a}^{c_{1}} f(\gamma(t)) \gamma^{\prime}(t) d t+\int_{c_{1}}^{c_{2}} f(\gamma(t)) \gamma^{\prime}(t) d t+\cdots+\int_{c_{n}}^{b} f(\gamma(t)) \gamma^{\prime}(t) d t
$$

## Proposition 4.3: Independence of Parametrization

Suppose $\gamma$ is a smooth curve parameterized in the same direction by both

$$
\gamma_{1}(t), a \leq t \leq b \quad \text { and } \quad \gamma_{2}(s), c \leq s \leq d s
$$

If $f$ is a complex function that is continuous on $\gamma$ then

$$
\int_{\gamma} f=\int_{a}^{b} f\left(\gamma_{1}(t)\right) \gamma_{1}^{\prime}(t) d t=\int_{c}^{d} f\left(\gamma_{2}(s)\right) \gamma_{2}^{\prime}(s) d s
$$

## Definition 4.4: Length of a Curve

The length of a smooth curve $\gamma$ is

$$
\text { length }(\gamma)=\int_{a}^{b}\left|\gamma^{\prime}(t)\right| d t
$$

for any parametrization $\gamma(t), a \leq t \leq b$ of $\gamma$.

## Proposition 4.7: Properties of the Integral

Suppose that $\gamma$ is a smooth curve, $f$ and $g$ are complex functions that are continuous on $\gamma$, and $c \in \mathbb{C}$.
(a) $\int_{\gamma} c f=c \int_{\gamma} f$ and $\int_{\gamma}(f+g)=\int_{\gamma} f+\int_{\gamma} g$
(b) If $\gamma$ is parameterized by $\gamma(t), a \leq t \leq b$, define the curve $-\gamma$ by $-\gamma(t)=\gamma(a+b-t), a \leq t \leq b$. Then $\int_{-\gamma} f=-\int_{\gamma} f$.
(c) If $\gamma_{1}$ and $\gamma_{2}$ are curves so that $\gamma_{2}$ starts where $\gamma_{1}$ ends, define $\gamma_{1} \gamma_{2}$ by following $\gamma_{1}$ to its end, then continuing on $\gamma_{2}$ to its end. Then $\int_{\gamma_{1} \gamma_{2}} f=\int_{\gamma_{1}} f+\int_{\gamma_{2}} f$.
(d) $\left|\int_{\gamma} f\right| \leq \max _{z \in \gamma}|f(z)| \cdot$ length $(\gamma)$

## $G$-Homotopic Curves

Let $G \subseteq \mathbb{C}$ be open and suppose that $\gamma_{0}$ and $\gamma_{1}$ are curves in $G$ parameterized by

$$
\gamma_{0}(t), 0 \leq t \leq 1 \quad \text { and } \quad \gamma_{1}(t), 0 \leq t \leq 1
$$

We say that $\gamma_{0}$ is $G$-homotopic to $\gamma_{1}$ if there exists a continuous function $h$ : $[0,1] \times[0,1] \rightarrow G$ such that $h(t, 0)=\gamma_{0}(t)$ and $h(t, 1)=\gamma_{1}(t)$ for all $t \in[0,1]$. We denote this by $\gamma_{0} \sim_{G} \gamma_{1}$, and the function $h$ is called a homotopy.

## Theorem 4.9: Cauchy's Theorem

Suppose that $G \subseteq \mathbb{C}$ is open, $f$ is holomorphic in $G$. If $\gamma_{0}$ and $\gamma_{1}$ are closed curves in $G$ with $\gamma_{0} \sim_{G} \gamma_{1}$ via a homotopy $h$ with continuous second partial derivatives, then

$$
\int_{\gamma_{0}} f=\int_{\gamma_{1}} f
$$

## $G$-Contractible Curve

Let $G \subseteq \mathbb{C}$ be open. A closed curve $\gamma$ is said to be $G$-contractible if $\gamma$ is $G$-homotopic to a point. This is denoted by $\gamma \sim_{G} 0$.

## Corollary 4.10:

Suppose that $G \subseteq \mathbb{C}$ is open, $f$ is holomorphic in $G$, and $\gamma \sim_{G} 0$ via a homotopy with continuous second partial derivatives. Then

$$
\int_{\gamma} f=0
$$

## Corollary 4.11:

If $f$ is entire and $\gamma$ is any smooth closed curve, then

$$
\int_{\gamma} f=0 .
$$

## Another Corollary: Independence of Path

Suppose that $G \subseteq \mathbb{C}$ is open and $f$ is holomorphic in $G$. If $\gamma_{0}$ and $\gamma_{1}$ are curves in $G$ parameterized by

$$
\gamma_{0}(t), 0 \leq t \leq 1 \quad \text { and } \quad \gamma_{1}(t), 0 \leq t \leq 1
$$

with $\gamma_{0} \sim_{G} \gamma_{1}, \quad \gamma_{0}(0)=\gamma_{1}(0)$ and $\gamma_{0}(1)=\gamma_{1}(1)$, then

$$
\int_{\gamma_{0}} f=\int_{\gamma_{1}} f
$$

## Positively Oriented Curve

A simple closed curve $\gamma$ is positively oriented if it is parameterized so that the inside of the curve is on the left of $\gamma$.

## Theorem 4.12: Cauchy's Integral Formula for a Circle

Let $C_{r}\left(z_{0}\right)$ be the counterclockwise oriented circle centered at $z_{0}$ and with radius $r$. If $f$ is holomorphic at each point of the closed disk bounded by $C_{r}\left(z_{0}\right)$, then

$$
f\left(z_{0}\right)=\frac{1}{2 \pi i} \int_{C_{r}\left(z_{0}\right)} \frac{f(z)}{z-z_{0}} d z
$$

## Theorem 4.13: Cauchy's Integral Formula

Suppose $f$ is holomorphic on the region $G, z_{0} \in G$ and $\gamma$ is a positively oriented, simple closed curve that is $G$-contractible and such that $z_{0}$ is enclosed by $\gamma$. Then

$$
f\left(z_{0}\right)=\frac{1}{2 \pi i} \int_{\gamma} \frac{f(z)}{z-z_{0}} d z
$$

## Corollary 4.14:

Suppose $f$ is holomorphic on and inside the circle $C_{r}\left(z_{0}\right)$ parameterized by $\gamma(\theta)=$ $z_{0}+r e^{i \theta}$ for $0 \leq \theta \leq 2 \pi$, then

$$
f\left(z_{0}\right)=\frac{1}{2 \pi} \int_{0}^{2 \pi} f\left(z_{0}+r e^{i \theta}\right) d \theta
$$

## Theorem 5.1:

Suppose $f$ is holomorphic on the region $G, z_{0} \in G$ and $\gamma$ is a positively oriented, simple closed curve that is $G$-contractible and such that $z_{0}$ is enclosed by $\gamma$. Then

$$
f^{\prime}\left(z_{0}\right)=\frac{1}{2 \pi i} \int_{\gamma} \frac{f(z)}{\left(z-z_{0}\right)^{2}} d z \quad \text { and } \quad f^{\prime \prime}\left(z_{0}\right)=\frac{1}{\pi i} \int_{\gamma} \frac{f(z)}{\left(z-z_{0}\right)^{3}} d z
$$

## Corollary 5.2:

If $f$ is differentiable in the region $G$, then $f$ is infinitely differentiable in $G$.

## Lemma 5.6:

Suppose $p(z)$ is a polynomial of degree $n$ with leading coefficient $a_{n}$. Then there is a real number $R_{0}$ such that

$$
\frac{1}{2}\left|a_{n}\right||z|^{n} \leq|p(z)| \leq 2\left|a_{n}\right||z|^{n}
$$

for all $z$ with $|z| \geq R_{0}$.

Theorem 5.7: Fundamental Theorem of Algebra
Every non-constant polynomial has a root in $\mathbb{C}$.

Corollary 5.9: Liouville's Theorem
Every bounded entire function is constant.

## Definition 5.11: Antiderivative of a Function

Let $G \subset \mathbb{C}$ be open and connected. For any functions $f, F: G \rightarrow \mathbb{C}$, if $F$ is holomorphic on $G$ and $F^{\prime}(z)=f(z)$ for all $z \in G$, then $F$ is an antiderivative of $F$ on $G$. An antiderivative of $f$ on $G$ will also sometimes be referred to as a primitive of $f$ on $G$.

## Theorem 5.13: Second Fundamental Theorem of Calculus

Suppose that $G \subset \mathbb{C}$ is open and connected, and $F$ is an antiderivative of $f$ on $G$. If $\gamma \in G$ is a smooth curve with parametrization $\gamma(t), a \leq t \leq b$, then

$$
\int_{\gamma} f(z) d z=F(\gamma(b))-F(\gamma(a))
$$

## Corollary 5.14: Independence of Path

If $f$ is holomorphic on a simply connected open set $G$, then $\int_{\gamma} f$ is independent of of the path $\gamma \in G$ between $z_{1}=\gamma(a)$ and $z_{2}=\gamma(b)$.

## Corollary 5.15:

Suppose $G \subseteq \mathbb{C}$ is open, $\gamma$ is a smooth closed curve in $G$, and $f$ has an antiderivative on $G$. Then $\int_{\gamma} f=0$.

## Theorem 5.17: First Fundamental Theorem of Calculus

Suppose $G \subseteq \mathbb{C}$ is a connected open set, and fix some basepoint $z_{0} \in G$. For each $z \in G$, let $\gamma_{z}$ denote a smooth curve in $G$ from $z_{0}$ to $z$. Let $f: G \rightarrow \mathbb{C}$ be a holomorphic function such that, for any simple closed curve $\gamma \in G, \int_{\gamma} f=0$. Then the function $F: G \rightarrow \mathbb{C}$ defined at any point $z \in G$ by

$$
F(z):=\int_{\gamma_{z}} f
$$

is holomorphic in $G$ with $F^{\prime}(z)=f(z)$. (The notation $:=$ means "defined by.")

## Definition 5.18: Simply Connected

A connected, open $G \subseteq \mathbb{C}$ is called simply connected if every simple closed curve in $G$ is $G$-contractible. That is, for any simple closed curve $\gamma \subseteq G$, the interior of $\gamma$ is completely contained in $G$.

## Corollary 5.19

Every holomorphic function on a simply connected open set has a primitive.

## Corollary 5.20: Morera's Theorem

Suppose $f$ is continuous in a connected open set $G$ and

$$
\int_{\gamma} f=0
$$

for all smooth closed paths $\gamma \subseteq G$. Then $f$ is holomorphic in $G$.

## Definition 7.1: Convergent and Divergent Sequences

Suppose $\left(a_{n}\right)$ is a sequence of complex numbers. If $a \in \mathbb{C}$ is such that for all $\varepsilon>0$ there is an integer $N$ for which $\left|a_{n}-a\right|<\varepsilon$ whenever $n \geq N$, then we say the sequence $\left(a_{n}\right)$ is convergent with limit $a$. We write

$$
\lim _{n \rightarrow \infty} a_{n}=a .
$$

If no such $a$ exists, then we say that $\left(a_{n}\right)$ is divergent.

## LEMMA 7.4

Let $\left(a_{n}\right)$ and $\left(b_{n}\right)$ be convergent sequences and let $c$ be any complex number. Then
(a) $\lim _{n \rightarrow \infty}\left(a_{n}+b_{n}\right)=\lim _{n \rightarrow \infty} a_{n}+\lim _{n \rightarrow \infty} b_{n}$ and $\lim _{n \rightarrow \infty} c a_{n}=c \lim _{n \rightarrow \infty} a_{n}$
(b) $\lim _{n \rightarrow \infty}\left(a_{n} \cdot b_{n}\right)=\lim _{n \rightarrow \infty} a_{n} \cdot \lim _{n \rightarrow \infty} b_{n}$
(c) If $\lim b_{n} \neq 0$ and $b_{n} \neq 0$ for any $n$, then $\lim _{n \rightarrow \infty}\left(\frac{a_{n}}{b_{n}}\right)=\frac{\lim _{n \rightarrow \infty} a_{n}}{\lim _{n \rightarrow \infty} b_{n}}$
(d) If $f$ is continuous at $a$, every $a_{n}$ is in the domain of $f$ and $\lim _{n \rightarrow \infty} a_{n}=a$, then $\lim _{n \rightarrow \infty} f\left(a_{n}\right)=f(a)$.

## Definition: Monotone Sequence

A sequence $\left(x_{n}\right)$ of real numbers is non-decreasing if $x_{k+1} \geq x_{k}$ for all $k=1,2,3, \ldots$, or non-increasing if $x_{k+1} \leq x_{k}$ for $k=1,2,3, \ldots$. A sequence that is either nondecreasing or non-increasing is called a monotone sequence.

## Axiom: Monotone Sequence Property

Any bounded monotone sequence converges.

## Theorem 7.6: Archimedean Property

If $x$ is any real number, then there is an integer $N$ that is greater than $x$.

## Lemma 7.7

Suppose $a, b \in \mathbb{C}$ and $p$ is a complex polynomial. Then

- $\lim _{n \rightarrow \infty} \frac{p(n)}{a^{n}}=0$
- $\lim _{n \rightarrow \infty} \frac{b^{n}}{n!}=0$


## Lemma 7.9

If $b_{k}$ are nonnegative real numbers then $\sum_{k=1}^{\infty} b_{k}$ converges if and only if the partial sums are bounded.

Lemma 7.10
If $\sum_{k=1}^{\infty} b_{k}$ converges, then $\lim _{k \rightarrow \infty} b_{k}=0$.
Lemma 7.11: (Test for Divergence)
If $\lim _{k \rightarrow \infty} b_{k} \neq 0$, then $\sum_{k=1}^{\infty} b_{k}$ diverges.

## Absolute Convergence

A series $\sum_{k=1}^{\infty} c_{k}$ is absolutely convergent if $\sum_{k=1}^{\infty}\left|c_{k}\right|$ converges.
Theorem 7.13
If a series converges absolutely, then it converges.

Lemma 7.16: p-series
$\sum_{k=1}^{\infty} \frac{1}{k^{p}}$ converges if $p>1$ and diverges if $p \leq 1$.

## Convergence of Sequences of Functions

Let $\left(f_{n}\right)$ be a sequence of functions defined on a set $G$. If, for each $z \in G$, the sequence $\left(f_{n}(z)\right)$ converges, then we say that the sequence $\left(f_{n}\right)$ converges pointwise on $G$. Suppose that $\left(f_{n}\right)$ and $f$ are functions defined on $G$. If for any $\varepsilon>0$ there is an $N$ such that for all $z \in G$ and $n \geq N$ we have

$$
\left|f_{n}(z)-f(z)\right|<\varepsilon
$$

then $\left(f_{n}\right)$ converges uniformly to $f$ on $G$.

## Proposition 7.18

Suppose $\left(f_{n}\right)$ is a sequence of functions that converges uniformly to a function $f$ on a set $G$. Then $f$ is continuous on $G$.

## Proposition 7.19

Suppose $f_{n}$ are continuous on the smooth curve $\gamma$ and converge uniformly on $\gamma$ to a function $f$. Then

$$
\lim _{n \rightarrow \infty} \int_{\gamma} f_{n}=\int_{\gamma} f
$$

## Lemma 7.20

If $\left(f_{n}\right)$ is a sequence of functions and $M_{n}$ is a sequence of constants so that $M_{n}$ converges to zero and $\left|f_{n}(z)\right| \leq M_{n}$ for all $z \in G$, then $\left(f_{n}\right)$ converges uniformly to zero on $G$.

## Lemma 7.21

If $\left(f_{n}\right)$ is a sequence of functions that converges uniformly to zero on $G$ and $z_{n}$ is any sequence in $G$, then the sequence $\left(f_{n}\left(z_{n}\right)\right)$ converges to zero.

Proposition 7.22
Suppose $\left(f_{k}\right)$ are continuous on the region $G,\left|f_{k}(z)\right| \leq M_{k}$ for all $z \in G$, and $\sum_{k=1}^{\infty} M_{k}$ converges. Then $\sum_{k=1}^{\infty} f_{k}$ converges absolutely and uniformly in $G$.

## Definition 7.24: Power Series

A power series centered at $z_{0}$ is a series of functions of the form $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$.

Lemma 7.25: Geometric Power Series
The series $\sum_{k=0}^{\infty} z^{k}$ (which is a power series centered at zero, with all $c_{k}$ equal to one) converges absolutely for $|z|<1$ to the function $\frac{1}{1-z}$. The convergence is uniform on any set of the form $\{z \in \mathbb{C}:|z| \leq r<1\}$.

## Theorem 7.26: Radius of Convergence

Any power series $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ has a radius of convergence $R$, with $0 \leq R \leq \infty$, such that
(a) if $r<R$, then $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ converges absolutely and uniformly on the closed disk $\bar{D}_{r}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right| \leq r\right\}$.
(b) if $\left|z-z_{0}\right|>R$ then the sequence of terms $c_{k}\left(z-z_{0}\right)^{k}$ is unbounded and $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ diverges.

## Corollary 7.27

Suppose the power series $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ has a radius of convergence $R$. Then the series represents a function that is continuous on the disk $D_{R}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<R\right\}$.

Corollary 7.28
Suppose the power series $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ has a radius of convergence $R$ and $\gamma$ is a smooth curve in $D_{R}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<R\right\}$. Then

$$
\int_{\gamma} \sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k} d z=\sum_{k=0}^{\infty} c_{k} \int_{\gamma}\left(z-z_{0}\right)^{k} d z
$$

In particular, if $\gamma$ is closed, then $\int_{\gamma} \sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k} d z=0$.

Theorem 7.30: Determining Radius of Convergence
For the power series $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$, the radius of convergence $R$ is given by

$$
R=\lim _{k \rightarrow \infty}\left|\frac{c_{k}}{c_{k+1}}\right| \quad \text { or } \quad R=\lim _{k \rightarrow \infty} \frac{1}{\left|c_{k}\right|^{1 / k}}
$$

These are the ratio test and root test for determining radius of convergence.

## Theorem 8.1

Suppose $f(z)=\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ has positive radius of convergence $R$. Then $f$ is holomorphic in $D_{R}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<R\right\}$.

## Theorem 8.2

Suppose $f(z)=\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ has positive radius of convergence $R$. Then

$$
f^{\prime}(z)=\sum_{k=1}^{\infty} k c_{k}\left(z-z_{0}\right)^{k-1}
$$

and the radius of convergence of this power series is also $R$.

## Corollary 8.5: Taylor Series Expansion

Suppose $f(z)=\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ has positive radius of convergence. Then

$$
c_{k}=\frac{f^{(k)}\left(z_{0}\right)}{k!}
$$

Corollary 8.6: Uniqueness of Power Series
If $\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ and $\sum_{k=0}^{\infty} b_{k}\left(z-z_{0}\right)^{k}$ are two power series that both converge to the same function $f(z)$ on an open disk centered at $z_{0}$, then $c_{k}=b_{k}$ for all $k$.

## Theorem 8.7

Suppose $f$ is a function that is holomorphic in $D_{R}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<R\right\}$. Then $f$ can be represented in $D_{R}\left(z_{0}\right)$ as a power series centered at $z_{0}$ (with a radius of convergence of at least $R$ ):

$$
f(z)=\sum_{k=0}^{\infty} c_{k}\left(z-z_{0}\right)^{k} \quad \text { with } \quad c_{k}=\frac{1}{2 \pi i} \int_{\gamma} \frac{f(w)}{\left(w-z_{0}\right)^{k+1}} d w
$$

Here $\gamma$ is any positively oriented, simple, closed, smooth curve in $D_{R}\left(z_{0}\right)$ for which $z_{0}$ is inside $\gamma$.

## Corollary 8.8

Suppose $f$ is holomorphic on the region $G, w \in G$ and $\gamma$ is a positively oriented simple, closed, smooth, $g$-contractible curve such that $z_{0}$ is inside $\gamma$, Then

$$
f^{(k)}\left(z_{0}\right)=\frac{k!}{2 \pi i} \int_{\gamma} \frac{f(z)}{\left(z-z_{0}\right)^{k+1}} d z
$$

## Corollary 8.9: Cauchy's Estimate

Suppose $f$ is holomorphic in $D_{R}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<R\right\}$ and $|f| \leq M$ there. Then

$$
\left|f^{(k)}(z)\right| \leq \frac{k!M}{R^{k}}
$$

for all $z \in \bar{D}_{R}\left(z_{0}\right)=\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<R\right\}$.

## Analytic Function

A function $f$ is analytic at a point $z_{0}$ if $f$ can be represented as a power series centered at $z_{0}$ and with radius $R>0 . \quad f$ is analytic in an open region $G$ if is analytic at every point of $G$.

## Theorem 8.10: Analytic "Equals" Holomorphic

A function $f$ is analytic at a point $z_{0}$ if and only if it is holomorphic at $z_{0} ; f$ is analytic on $G$ if and only if it is holomorphic on $G$.

## Theorem 8.11: Classification of Zeros

Suppose $f$ is a holomorphic function defined on an open set $G$ and suppose that $f$ has a zero at some point $z_{0} \in G$. Then there are exactly two possibilities: Either
(a) $f$ is identically zero on some open disk $D$ centered at $z_{0}$, or
(b) there is a positive integer $m$ and a holomorphic function $g$, defined on $G$, satisfying $f(z)=\left(z-z_{0}\right)^{m} g(z)$ for all $z \in G$, with $g\left(z_{0}\right)=0$.

The integer $m$ in the second case is uniquely determined by $f$ and $z_{0}$, and is called the multiplicity of the zero of $f$ at $z_{0}$.

## Theorem 8.12: The Identity Principle

Suppose $f$ and $g$ are holomorphic on the region $G$ and $f\left(z_{k}\right)=g\left(z_{k}\right)$ for a sequence that converges to $w \in G$, with $z_{k} \neq w$ for any $k$. Then $f(z)=g(z)$ for all $z \in G$.

## Theorem 8.13: Maximum-Modulus Theorem

Suppose $f$ is holomorphic and non-constant on the closure of a bounded region $G$. Then $|f|$ only attains its maximum on the boundary of $G$.

## Theorem 8.15: Maximum-Modulus Theorem

Suppose $f$ is holomorphic and non-constant on the closure of a bounded region $G$. Then $|f|$ only attains its minimum on the boundary of $G$.

## Definition 8.16: Laurent Series

A Laurent series centered at $z_{0}$ is a series of the form $\sum_{k=-\infty}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$.

## Theorem 8.19

Suppose $f$ is a function that is holomorphic in the annulus

$$
A=\left\{z \in \mathbb{C}: R_{1}<\left|z-z_{0}\right|<R_{2}\right\}
$$

Then $f$ can be represented in $A$ as a Laurent series centered at $z_{0}$ :

$$
f(z)=\sum_{k=-\infty}^{\infty} c_{k}\left(z-z_{0}\right)^{k} \quad \text { with } \quad c_{k}=\frac{1}{2 \pi i} \int_{\gamma} \frac{f(w)}{\left(w-z_{0}\right)^{k+1}} d w
$$

Here $\gamma$ is any circle in $A$ that is centered at $z_{0}$ (or any other closed, smooth path that is $A$-homotopic to such a circle).

## Theorem 8.20

For a given function in a given region of convergence, the coefficients of the corresponding Laurent series are uniquely determined.

## Definition 9.1: Classification of Singularities

If $f$ is holomorphic in the punctured disk $\left\{z \in \mathbb{C}: 0<\left|z-z_{0}\right|<R\right\}$ for some $R>0$ but not at $z=z_{0}$, then $z_{0}$ is an isolated singularity of $f$. The singularity $z_{0}$ is called
(a) a removable singularity if there is a function $g$, that is holomorphic in the set $\left\{z \in \mathbb{C}:\left|z-z_{0}\right|<R\right\}$, such that $f=g$ in the set $\left\{z \in \mathbb{C}: 0<\left|z-z_{0}\right|<R\right\}$,
(b) a pole if $\lim _{z \rightarrow z_{0}}|f(z)|=\infty$,
(c) an essential singularity if $z_{0}$ is neither removable or a pole.

## Proposition 9.5

Suppose $z_{0}$ is an isolated singularity of $f$. Then
(a) $z_{0}$ is removable if and only if $\lim _{z \rightarrow z_{0}}\left(z-z_{0}\right) f(z)=0$;
(b) $z_{0}$ is pole if and only if it is not removable and $\lim _{z \rightarrow z_{0}}\left(z-z_{0}\right)^{n+1} f(z)=0$ for some positive integer $n$. The smallest possible such $n$ is called the order of the pole.

## Theorem 9.6; The Casorati-Weierstrass Theorem

If $z_{0}$ is an essential singularity of $f$ and $D=\left\{z \in \mathbb{C}: 0<\left|z-z_{0}\right|<R\right\}$ for some $R>0$, then any $w \in \mathbb{C}$ is arbitrarily close to a point in $f(D)$. That is, for any $w \in \mathbb{C}$ and any $\varepsilon>0$ there exists a $z \in D$ such that $|w-f(z)|<\varepsilon$.

## Proposition 9.7

Suppose $z_{0}$ is an isolated singularity of $f$ having Laurent series $\sum_{k=-\infty}^{\infty} c_{k}\left(z-z_{0}\right)^{k}$ that is valid in some set $\left\{z \in \mathbb{C}: 0<\left|z-z_{0}\right|<R\right\}$. Then
(a) $z_{0}$ is removable if and only if there are no negative exponents (that is, the Laurent series is a power series);
(b) $z_{0}$ is pole if and only if there are finitely many negative exponents, and the order of the pole is the largest value of $k$ such that $c_{-k} \neq 0$;
(c) $z_{0}$ is an essential singularity if and only if there are infinitely many negative exponents.

